

Compressed Sensing - beyond the Shannon Paradigm

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joint work with Albert Cohen and Ron DeVore

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1 Motivation, Background

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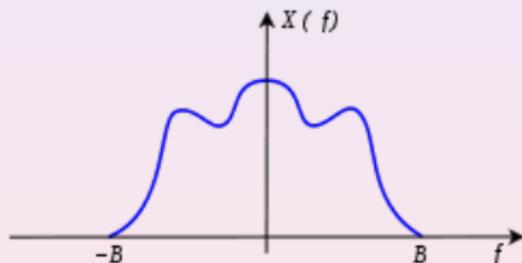
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The Nyquist-Shannon Theorem

A bandlimited “signal” $f(t)$, $t \in \mathbb{R}$, with bandwidth $2B$ can be reconstructed exactly from the samples $f(k\tau)$, $\tau < 1/2B$, ...

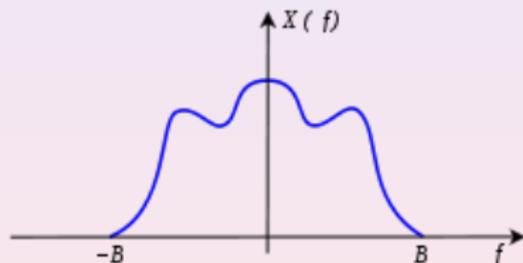
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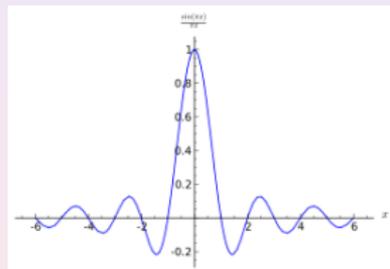
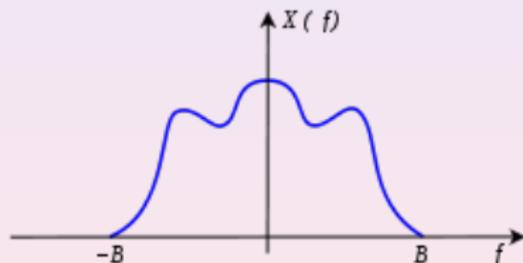


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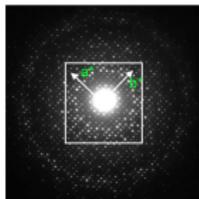
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- ...measurements are difficult/expensive/harmful

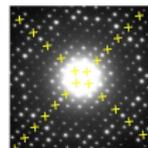
(Information-)Sparse Signals

...are those sparse?

[001] SAED Pattern of Phase M1

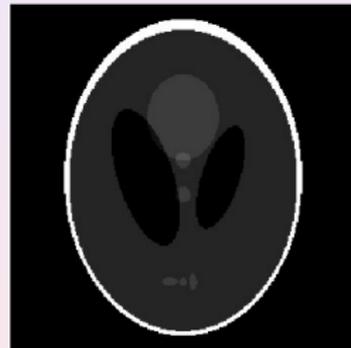
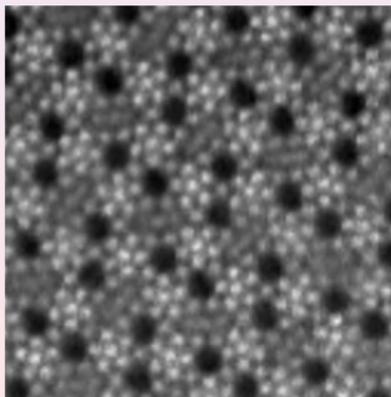


$a = 21.2 \text{ \AA}$
 $b = 26.6 \text{ \AA}$



$h00; h = 2n$
 $0k0; k = 2n$
a-glide \perp b and b-glide \perp a
or 2₁ screw along both a and b axes

DeSanto et al., Topics in Catal. 23 (1-4), 23 (2003); Z. Natur 210, 150-165 (2004). 



Attempt of a “Shortcut”

- employ **more general** measurements than classical sampling

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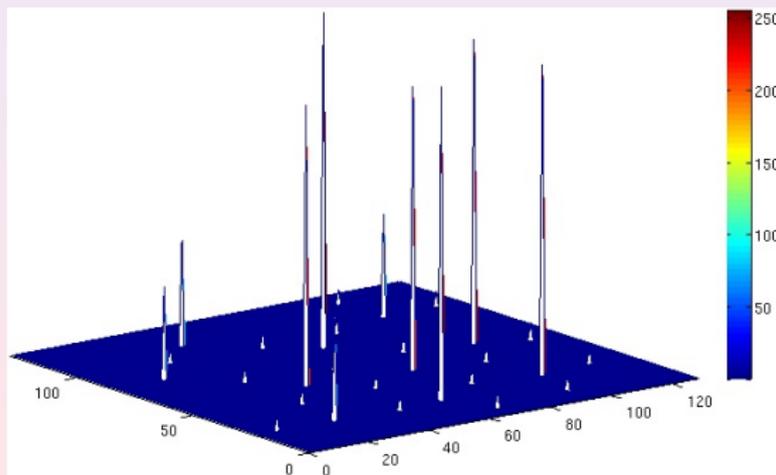
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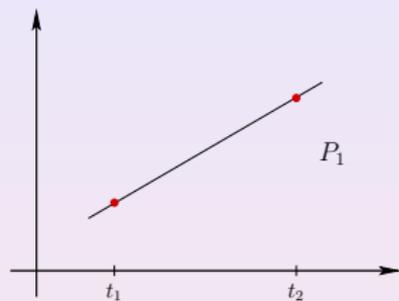
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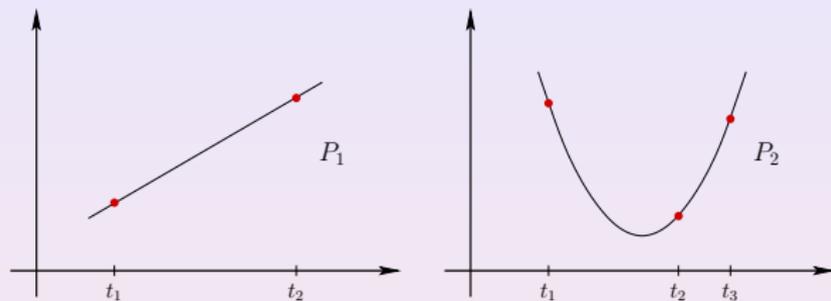
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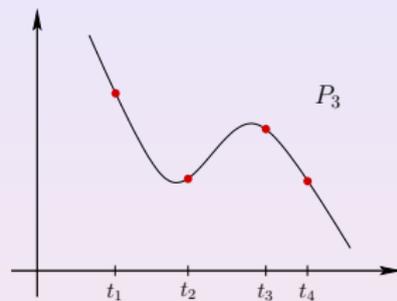
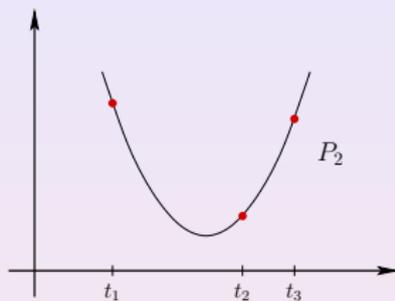
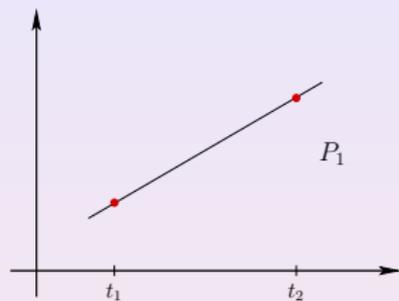
An Instructive Example: Polynomials



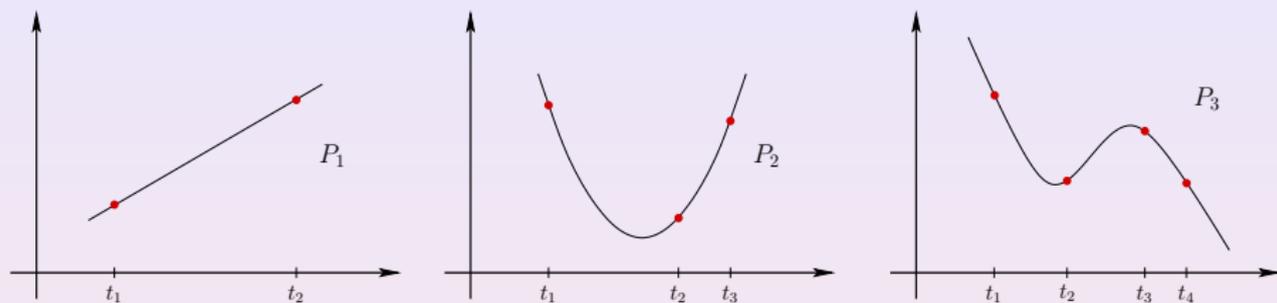
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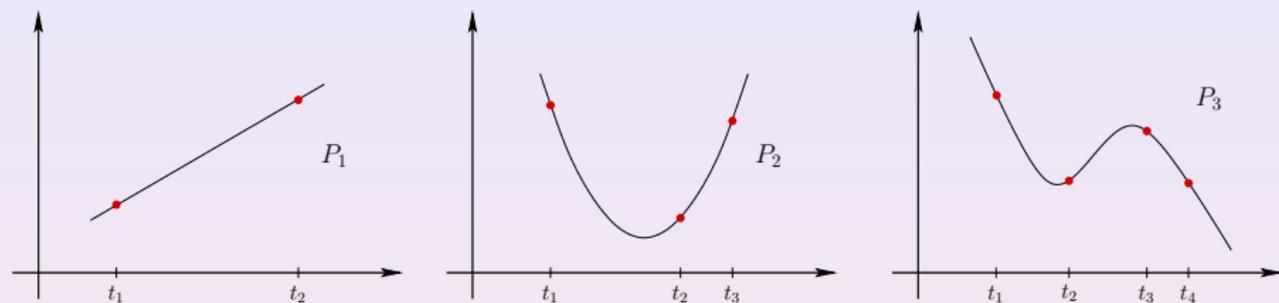


An Instructive Example: Polynomials



$$P_{N-1}(t) = x_1 t^0 + x_2 t^1 + x_3 t^2 + \dots + x_{N-1} t^{N-2} + x_N t^{N-1}$$

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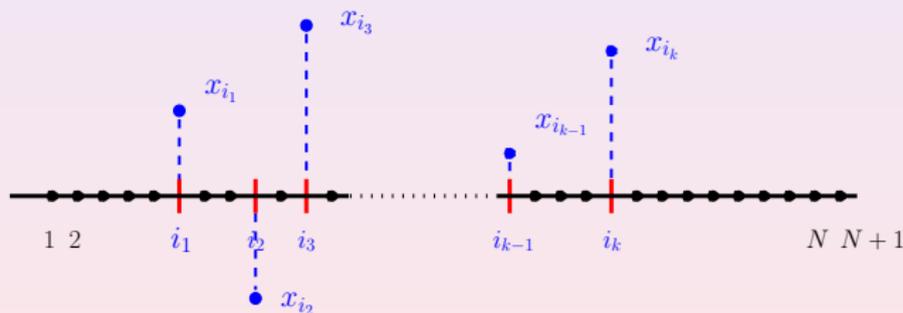
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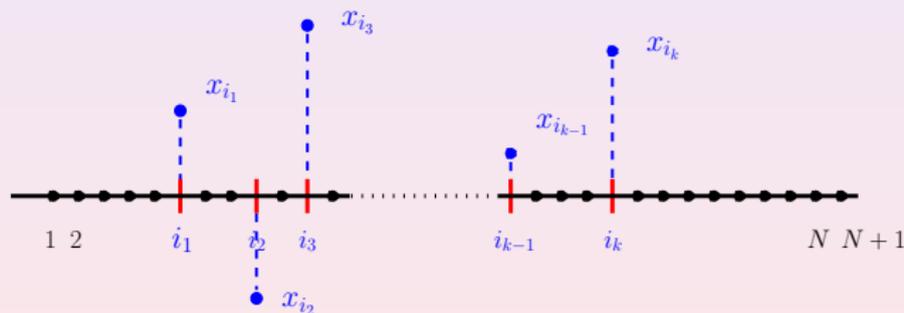
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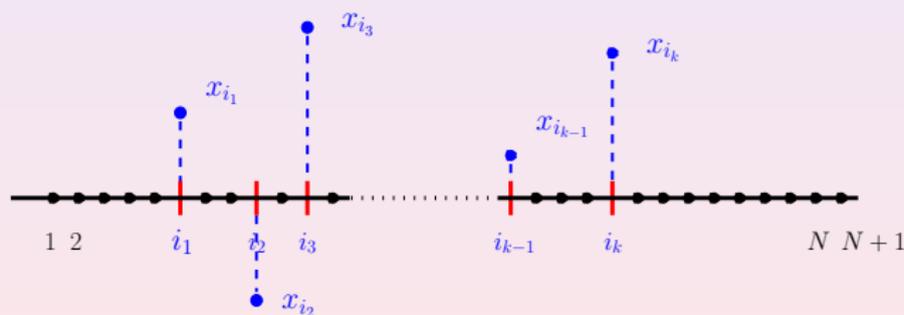


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The Mathematical Model

- $x = (x_1, \dots, x_N)^T \in \mathbb{R}^N$ “large” signal

Candés/Romberg/Tao, Donoho, Gilbert/Strauss/Tropp, Tanner,
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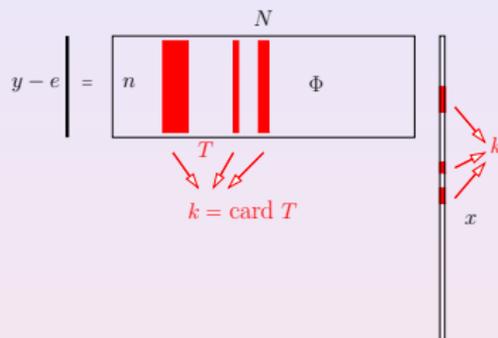
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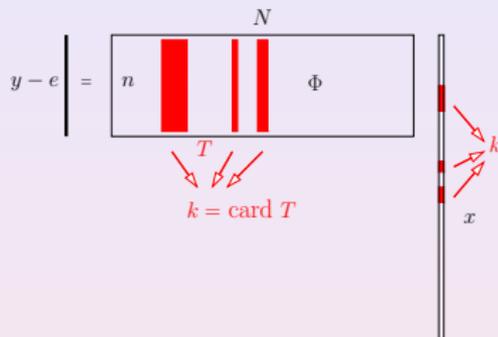
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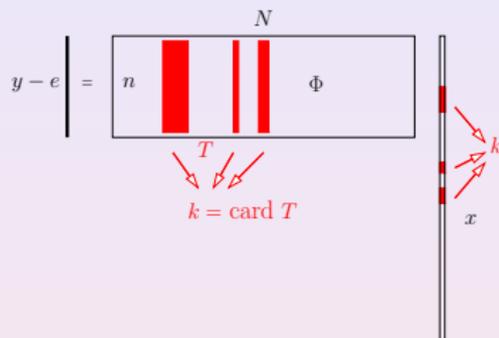


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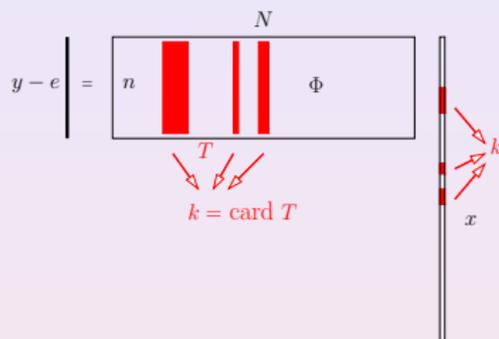
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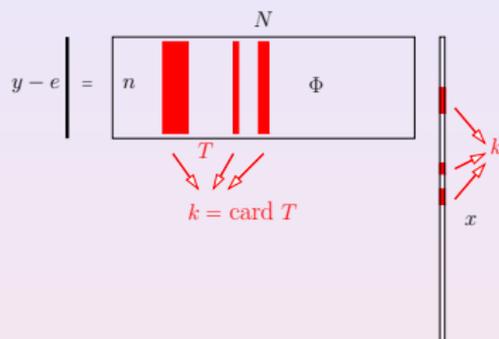
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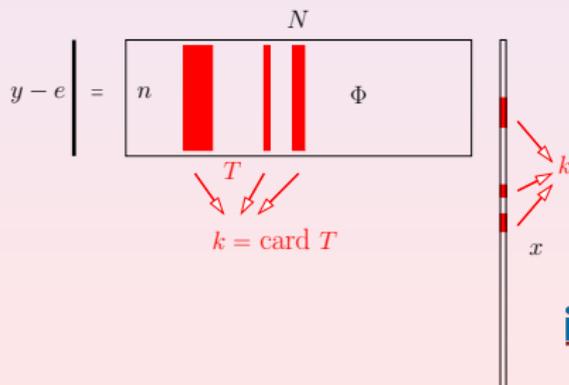
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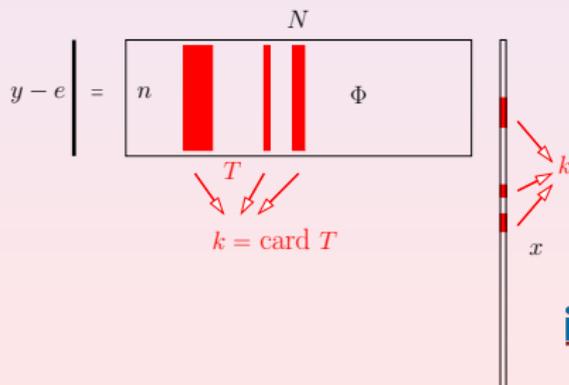
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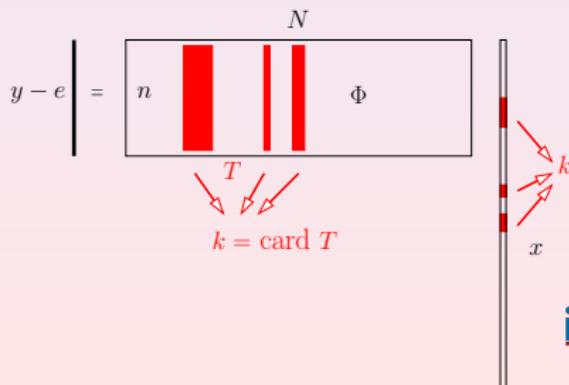


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- (iii) For any set of columns T with $\#T = 2k$, the matrix Φ_T has rank $2k$.

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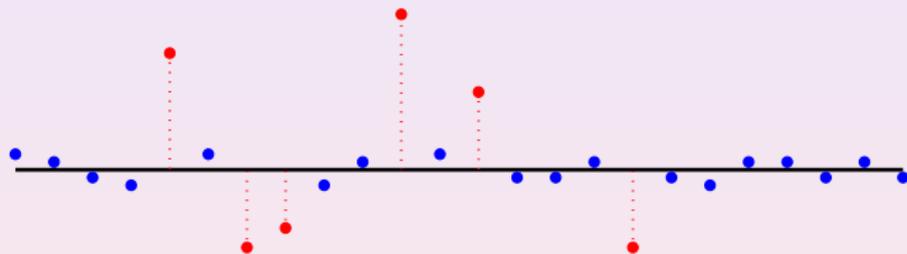
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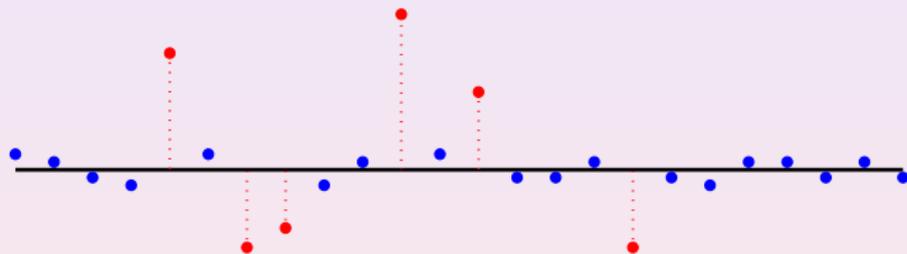
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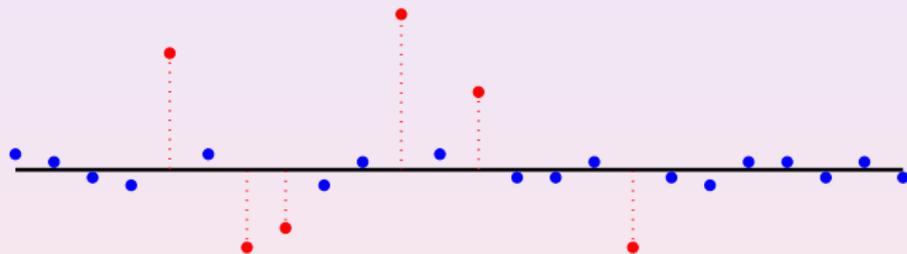
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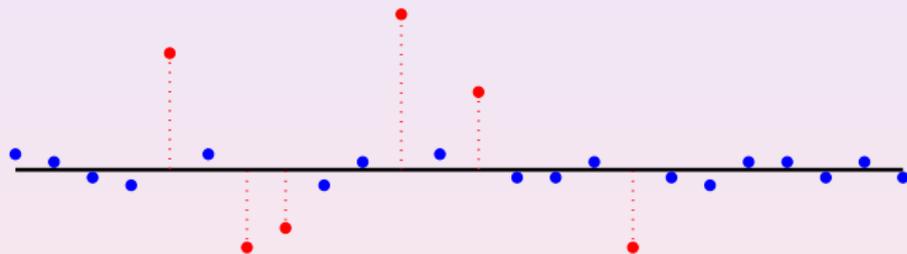


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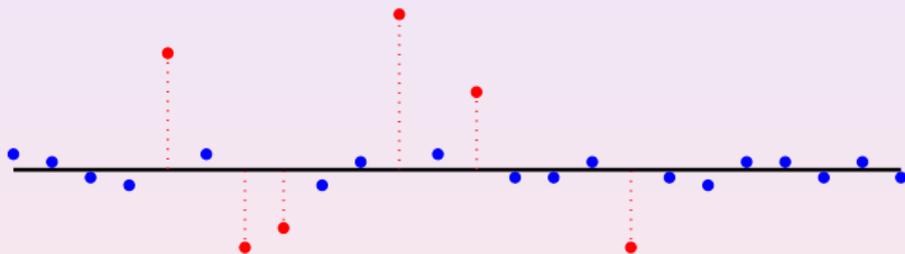


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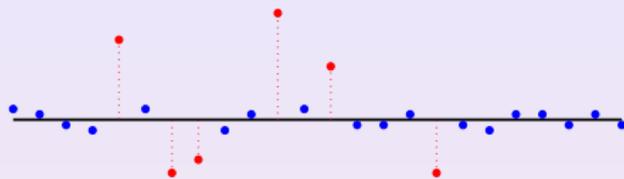
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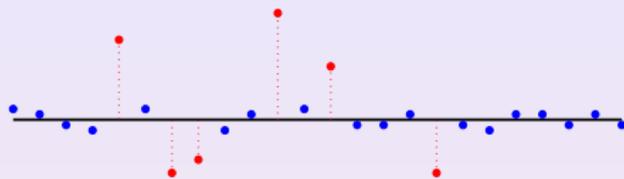
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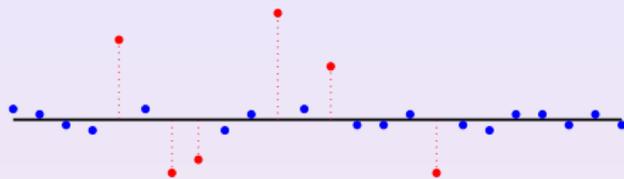


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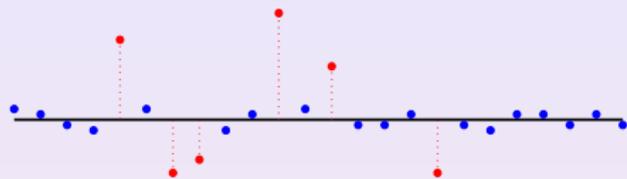
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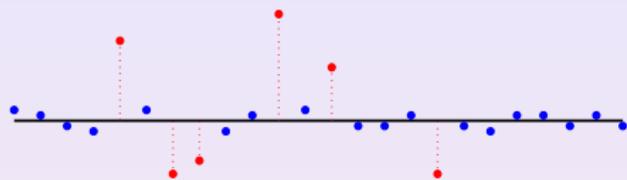
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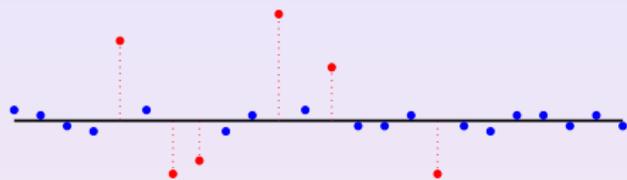
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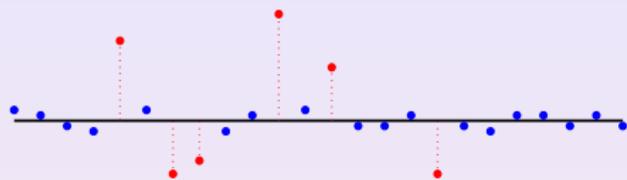
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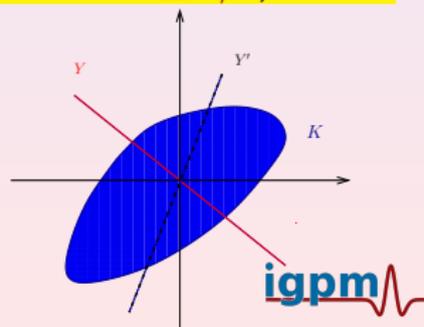
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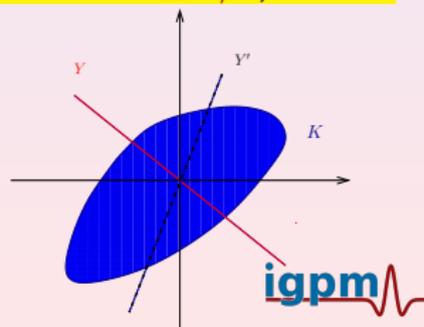
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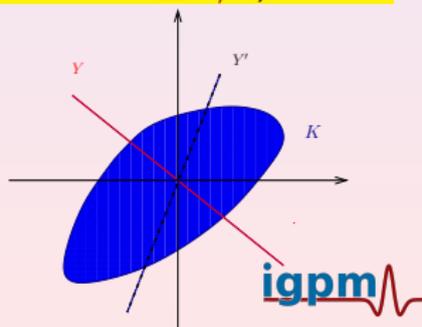
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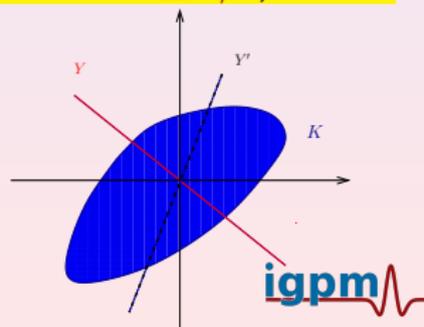
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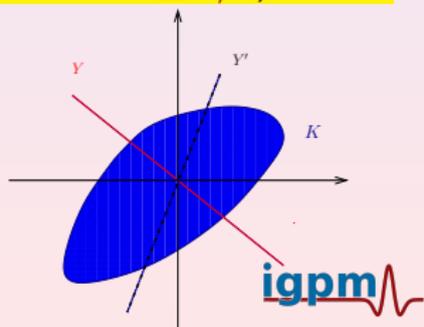
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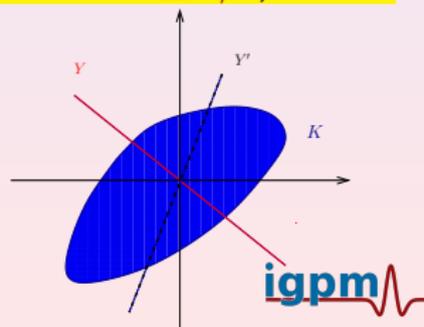
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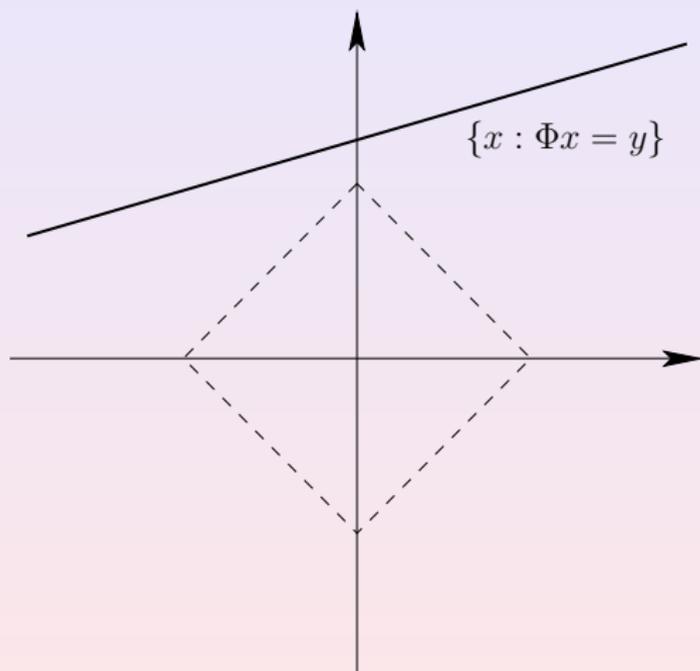
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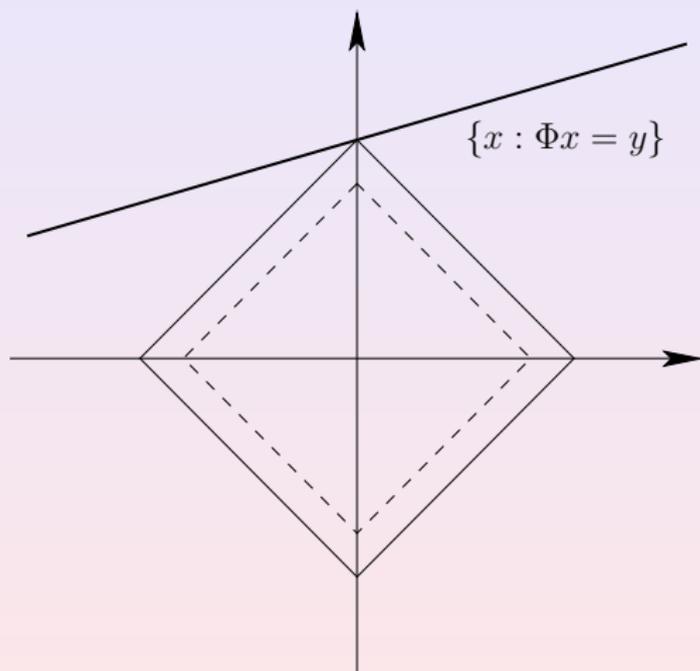
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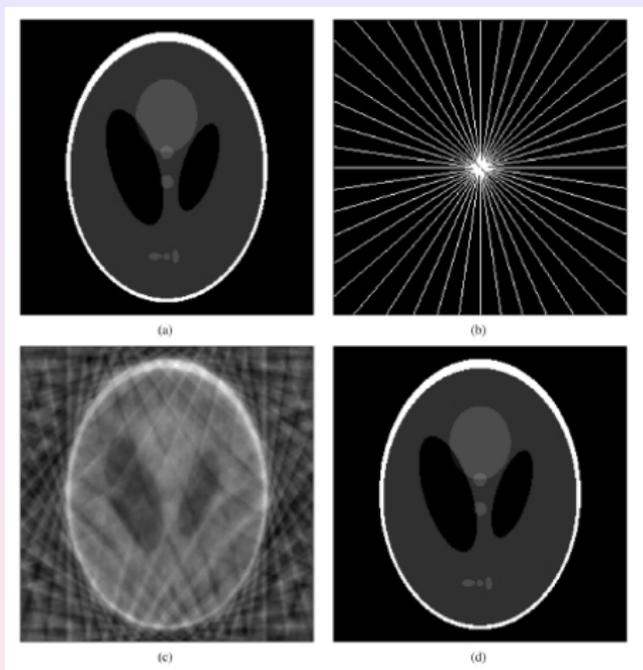
Convex relaxation: $\min \|\cdot\|_{\ell_0} \rightarrow \min \|\cdot\|_{\ell_1}$

A Geometric Explanation - $n = 1, N = 2$



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(Candes/Romberg/Tao)

The “Rice - One Pixel - Camera”

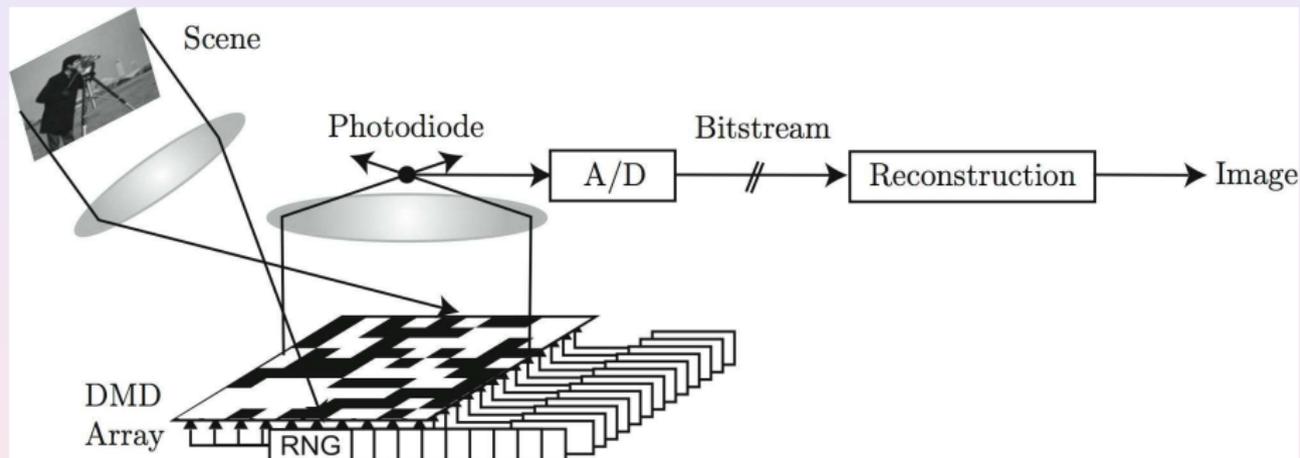


Figure: (R. Baraniuk, Rice University)

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Gaussian matrices: $\phi_{i,j} \in \mathcal{N}(0, 1/n)$

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Gauß-, Bernoulli-, uniformly distributed points on the $(n-1)$ -sphere satisfy **CoMP**

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take $x^{j+1} = \text{best } k\text{-term approximation of } \hat{x}$ und $\Lambda_{j+1} := \operatorname{supp} x^{j+1}$, set $j + 1 \rightarrow j$, and go to (ii).

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- ℓ_1 -minimization/regularization is more robust but more expensive...

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$$t(n_1, n_2) = Jb_2e^{-c_2n_2/2} + b_1(e^{-n_1\frac{c_1}{32}} + e^{-c_1n_1} + e^{-c_1n_1/2})$$

