

5.2. Cluster Analysis

- o Aim: group n objects into k classes
- o $k \leq n$, k often unknown
- o Objects within classes are "close" to each other,
objects in different classes are well distinguishable.
- o Needed: metric to define closeness vs. discriminable.

5.2.1 k -means clustering

~~Aim:~~ Given $x_1, \dots, x_n \in \mathbb{R}^P$

Aim: Partition data into clusters S_1, \dots, S_k ,

S_1, \dots, S_k a partition of $\{1, \dots, n\}$,

with centers $\mu_1, \dots, \mu_k \in \mathbb{R}^P$ as solution to

$$\min_{S_1, \dots, S_k \text{ part.}} \sum_{l=1}^k \sum_{i \in S_l} \|x_i - \mu_l\|^2$$

μ_1, \dots, μ_k

Given the partition, the optimal centers $\bar{x}_l = \frac{1}{n_l} \sum_{i \in S_l} x_i$.

k -means algorithm, Lloyd's algorithm

Alternate between:

- Given centers μ_1, \dots, μ_k assign each point x_i to cluster $l = \arg \min_j \|x_i - \mu_j\|$
- Update the centers $\mu_l = \frac{1}{|S_l|} \sum_{i \in S_l} x_i$

- > needs to know the no. of clusters k a-priori
- > needs Euclidean space
- > may end in suboptimal solutions
- > solution has always convex clusters



5.2.2. Spectral clustering

To overcome these difficulties.

Given x_1, \dots, x_4 .

Construct a weighted graph $G = (V, E, w)$

Each point x_i is a vertex v_i , $i = 1, \dots, 4$

Edges weights w_{ij} are $w_{ij} = K_\epsilon(\|x_i - x_j\|)$

with Kernel K_ϵ , e.g., $K_\epsilon(u) = \exp(-\frac{1}{2\epsilon} u^2)$.

Note: $\|x_i - x_j\|$ can be substituted by any dissimilarity measure.

Consider a random walk with transition matrix

$$M = D^{-1} W$$

$$P(X_{t+1} = j | X_t = i) = \frac{w_{ij}}{\deg(i)} = M_{ij}$$

$$D = \text{diag}(\deg(i)) , \deg(i) = \sum_{j=1}^n w_{ij} .$$

$$\text{Decompose } M = \Phi \Lambda \Psi^\top = \sum_{k=1}^n \lambda_k e_k \psi_k^\top$$

$$\Lambda = \text{diag}(\lambda_1, \dots, \lambda_n), \lambda_1 \geq \dots \geq \lambda_n$$

$$\Phi = (e_1, \dots, e_n), \Psi = (\psi_1, \dots, \psi_n)$$

biorthonormal system, right/left eigenvectors.

$$\text{Then } M^t = \sum_{k=1}^n \lambda_k^t e_k \psi_k^\top$$

$m_j^{(t)}$ distribution of being in vertex j
having started in i

$$v_i \rightarrow e_i^\top M^t = \sum_{k=1}^n \lambda_k^t e_i^\top e_k \psi_k^\top = \underbrace{\sum_{k=1}^n \lambda_k^t e_{k,i} \underbrace{\psi_k^\top}_{\text{coefficient orth. basis}}}$$

Recall: if v_i, v_j close / strongly connected, then
 $e_i^\top M^t$ and $e_j^\top M^t$ are similar.

Diffusion map truncated to d dimensions

$$\phi_t^{(d)}(i) = \begin{pmatrix} \lambda_2^t e_{2,i} \\ \vdots \\ \lambda_d^t e_{d,i} \end{pmatrix} \quad (\text{see 4.3})$$

Aim: cluster vertices of the graph into k clusters.

Algorithm 5.3. (Spectral clustering)

Given a graph $G = (V, E, W)$, no. of clusters k, t .

Compute the $(k-1)$ -dim. diff. map

$$\phi_t^{(k-1)}(i) = \begin{pmatrix} \lambda_2^t e_{1,i} \\ \vdots \\ \lambda_k^t e_{k,i} \end{pmatrix}$$

and cluster $\phi_t^{(k-1)}(1), \dots, \phi_t^{(k-1)}(n) \in \mathbb{R}^{k-1}$

using, e.g., k-means clustering. |

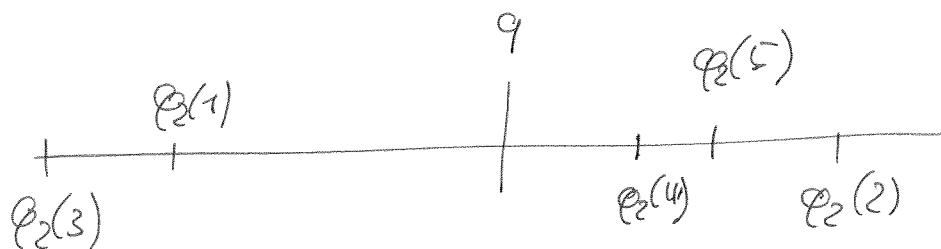
Particularly for two clusters S, S^c :

$$\phi_t^{(1)}(i) \in \mathbb{R}^1, i=1, \dots, n$$

will be on a line. Natural way of clustering on a line is to define a threshold q such that

$v_i \in S$ if $\phi_t^{(1)}(i) \leq q$.

e.g. for 5 points



5.2.3 Hierarchical clustering

Given n objects v_1, \dots, v_n and pairwise dissimilarities

$$\delta_{ij} = \delta_{ji}, \quad \Delta = (\delta_{ij})_{ij=1, \dots, n}$$

Define a linkage function between clusters C_1, C_2

$$d(C_1, C_2) = \begin{cases} \min_{i \in C_1, j \in C_2} \delta_{ij} & \text{single linkage} \\ \max_{i \in C_1, j \in C_2} \delta_{ij} & \text{complete linkage} \\ \frac{1}{|C_1||C_2|} \sum_{i \in C_1, j \in C_2} \delta_{ij} & \text{average linkage} \end{cases}$$

Algorithm (Agglomerative Clustering)

Initialize clusters as singletons : For $i=1$ to n do $C_i \leftarrow \{v_i\}$

Initialize set of clusters available for merging : $S \leftarrow \{1, \dots, n\}$

repeat

Pick 2 most similar cluster to merge : $(j, k) \leftarrow \arg \min_{j, k \in S} d(C_j, C_k)$

Create new cluster $C_e \leftarrow C_j \cup C_k$

Mark j and k as unavailable : $S \leftarrow S \setminus \{j, k\}$

if $C_e \neq \{1, \dots, n\}$ then

Mark ℓ as available , $S \leftarrow S \cup \{\ell\}$

For each $i \in S$ do

Update dissimilarities $d(C_i, C_e)$

Table 13.2.3 Mahalanobis distances D_{ij} between 10 island races of white-toothed shrews (from Delany and Healy, 1966; Gower and Ross, 1969)

		Scilly Islands					Channel Islands			France	
		1	2	3	4	5	6	7	8	9	10
Scilly Islands	1. Tresco	0									
	2. Bryher	1.61	0								
	3. St Agnes	1.97	2.02	0							
	4. St Martin's	1.97	2.51	2.88	0						
	5. St Mary's	1.40	1.70	1.35	2.21	0					
Channel Islands	6. Sark	2.45	3.49	3.34	3.83	3.19	0				
	7. Jersey	2.83	3.94	3.64	2.89	3.01	3.00	0			
	8. Alderney	9.58	9.59	10.05	8.78	9.30	9.74	9.23	0		
French mainland	9. Guernsey	7.79	7.82	8.43	7.08	7.76	7.86	7.76	2.64	0	
	{10. Cap Gris Nez	7.86	7.92	8.36	7.44	7.79	7.90	8.26	3.38	2.56	0

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Table 13.3.1 Single linkage procedure

Order	Distances (ordered)	Clusters
1	$d_{35} = 1.35$	(1), (2), (3, 5), (4), (6), (7), (8), (9), (10)
2	$d_{15} = 1.40$	(1, 3, 5), (2), (4), (6), (7), (8), (9), (10)
3	$d_{12} = 1.61$	(1, 2, 3, 5), (4), (6), (7), (8), (9), (10)
4	$d_{25} = 1.70$	(1, 2, 3, 5), (4), (6), (7), (8), (9), (10)†
5‡	$d_{14} = 1.969$	(1, 2, 3, 4, 5), (6), (7), (8), (9), (10)
6‡	$d_{13} = 1.972$	(1, 2, 3, 4, 5), (6), (7), (8), (9), (10)†
7	$d_{23} = 2.02$	(1, 2, 3, 4, 5), (6), (7), (8), (9), (10)†
8	$d_{45} = 2.21$	(1, 2, 3, 4, 5), (6), (7), (8), (9), (10)†
9	$d_{16} = 2.45$	(1, 2, 3, 4, 5, 6), (7), (8), (9), (10)
10	$d_{24} = 2.51$	(1, 2, 3, 4, 5, 6), (7), (8), (9), (10)†
11	$d_{9,10} = 2.56$	(1, 2, 3, 4, 5, 6), (7), (8), (9, 10)
12	$d_{89} = 2.64$	(1, 2, 3, 4, 5, 6), (7), (8, 9, 10)
13	$d_{17} = 2.84$	(1, 2, 3, 4, 5, 6, 7), (8, 9, 10)
14	$d_{34} = 2.88$	(1, 2, 3, 4, 5, 6, 7), (8, 9, 10)†
15	$d_{47} = 2.89$	(1, 2, 3, 4, 5, 6, 7), (8, 9, 10)†
16	$d_{67} = 3.00$	(1, 2, 3, 4, 5, 6, 7), (8, 9, 10)†
.	.	.
.	.	.
45	$d_{49} = 7.08$	(1, 2, 3, 4, 5, 6, 7, 8, 9, 10)

† No new clusters.

‡ More accurate values of distances to break the tie.

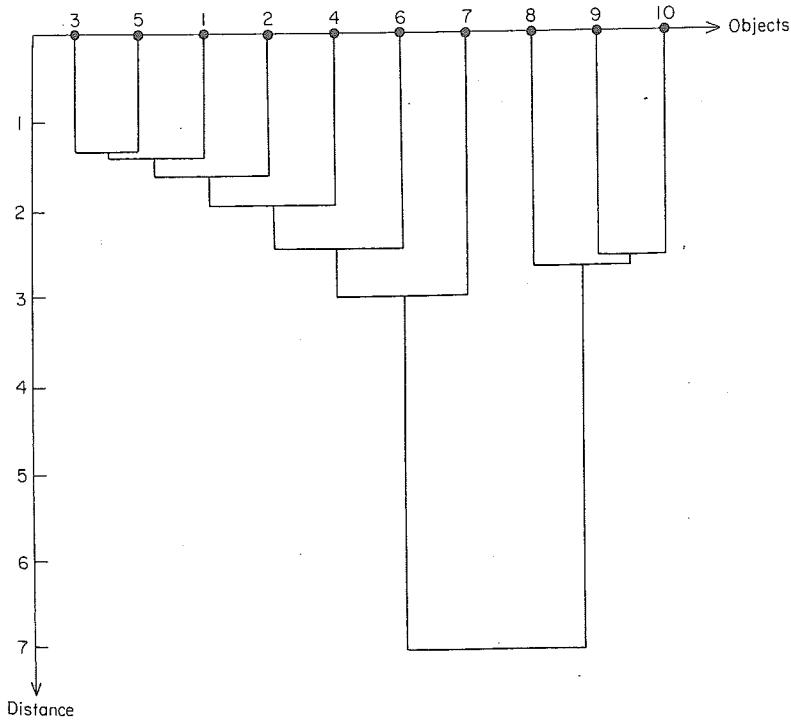


Figure 13.3.1 Dendrogram for shrew data (single linkage).

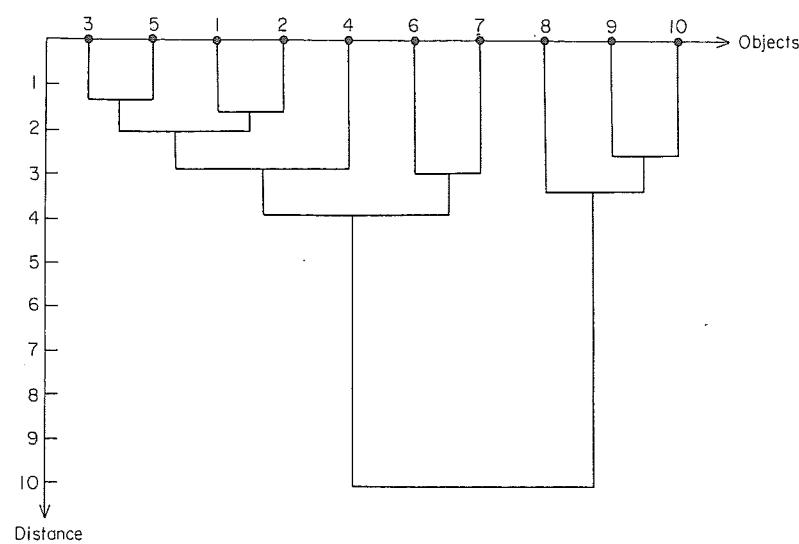


Figure 13.3.2 Dendrogram for the shrew data (complete linkage).

Visualizations by dendograms or binary trees.

6. Support Vector Machines (SVM)

- SVM learning alg. among the best "off-the-shelf" supervised learning algorithms.
- Application of kernels makes SVM very flexible.

Advantages:

- effective in high-dim. spaces
- also effective if no. of attr. \geq no. of samples
- uses only a subset of points in the decision fn. (called support vectors), also memory efficient.

Given a training set $(x_1, y_1), \dots, (x_n, y_n)$,

$x_i \in \mathbb{R}^P$, $y_i \in \{-1, +1\}$.

data points class membership

Key idea: select a particular hyperplane that separates the points into two classes and maximizes the margin, i.e., the distance between the hyperplane and the closest point of the training set.

