

6.4. SUM - soft margins

$$(P) \quad \min_{\alpha \in \mathbb{R}^n, b, \xi \in \mathbb{R}} \left\{ \frac{1}{2} \|\alpha\|^2 + C \sum_{i=1}^n \xi_i \right\} \quad (C \text{ parameters})$$

s.t. $y_i (\alpha^\top x_i + b) \geq 1 - \xi_i$
 $\xi_i \geq 0, i = 1, \dots, n$

Consequences

- $\xi_i > 1 \Rightarrow$ misclassification
- $0 < \xi_i \leq 1 \Rightarrow$ correctly classified, but lies in the margin

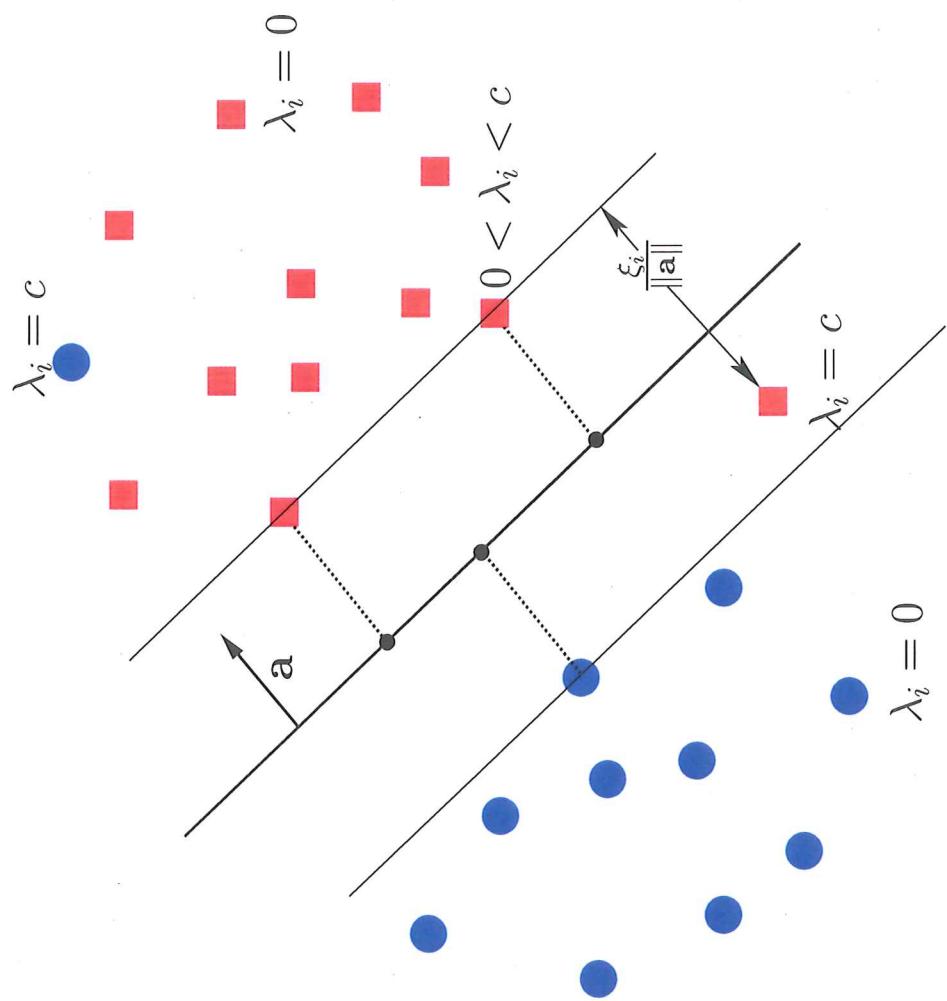
$$(D) \quad \max_{\lambda} \left\{ \sum_{i=1}^n \lambda_i - \frac{1}{2} \sum_{i,j=1}^n y_i y_j \lambda_i \lambda_j x_i^\top x_j \right\}$$

s.t. $0 \leq \lambda_i \leq C, i = 1, \dots, n$
 $\sum_{i=1}^n \lambda_i y_i = 0$

Investigating complementary slackness

- $0 < \lambda_i < C \Rightarrow y_i (\alpha^\top x_i + b) = 1$ (margin SVs)
- $\lambda_i = C \Rightarrow y_i (\alpha^\top x_i + b) = 1 - \xi_i, \xi_i \geq 0$ (margin error)
- $\lambda_i = 0 \Rightarrow y_i (\alpha^\top x_i + b) \geq 1$ (non SVs)

Hence, the solution is sparse, most of the points have $\lambda_i = 0$.



6.5. The SMO-Algorithm

Sequential Minimal Optimization To solve the dual problem.

$$(1) \quad \max_{\lambda} W(\lambda) = \sum_{i=1}^n \lambda_i - \frac{1}{2} \sum_{i,j} y_i y_j \lambda_i \lambda_j x_i^T x_j$$

s.t. $0 \leq \lambda_i \leq C$

$$\sum_{i=1}^n \lambda_i y_i = 0$$

Assume λ is a feasible point, i.e., λ satisfies the constraints.

Idea: "cyclic coordinatewise optimization" does not work, since, e.g.,

$$\lambda_1 y_1 = - \sum_{i=2}^n \lambda_i y_i \text{ or } \lambda_1 = -y_1 \sum_{i=2}^n \lambda_i y_i$$

Hence each λ_j is determined by fixing λ_i , $i \neq j$.

Idea: update at least two λ_j simultaneously \rightarrow SMO alg.

(SMO) - repeat

1. Select a pair (i, j) to update next (the one which promises most progress)
2. Optimize $W(\lambda)$, w.r.t. λ_i and λ_j while holding λ_k , $k \neq i, j$, fixed until convergence

Check KKT within a tolerance limit

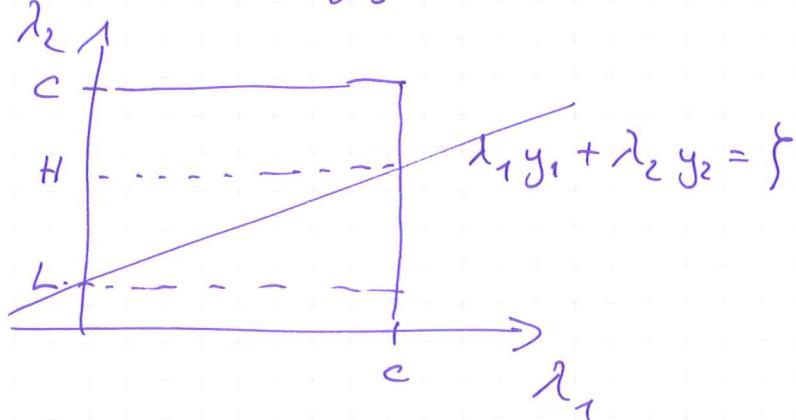
$\epsilon = 0.01$ or 0.001 , to verify convergence.

Optimize $\omega(\lambda)$ w.r.t. λ_1, λ_2 with $\lambda_3, \dots, \lambda_n$ fixed,
 λ feasible.

It holds

$$\lambda_1 y_1 + \lambda_2 y_2 = -\sum_{i=3}^n \lambda_i y_i = \varsigma, \quad \varsigma \text{ fixed.}$$

~~BB~~



Denote $0 \leq \lambda_1, \lambda_2 \leq c$ (*)
 $L \leq \lambda_2 \leq H$

Moreover $\lambda_1 = (\varsigma - \lambda_2 y_2) y_1$ (**)

Hence: $\omega(\lambda_1, \dots, \lambda_n) = \omega((\varsigma - \lambda_2 y_2) y_1, \underbrace{\lambda_3, \dots, \lambda_n}_{\text{fixed}})$
 is a quadratic function of λ_2 .

It can be written as (remember: $y_i \in \{-1, 1\}$)

$$g_2 \lambda_2^2 + g_1 \lambda_2 + g_0, \quad g_0, g_1, g_2 \text{ appropriate}$$

Determine the max. by differentiation.

$$2g_2 \lambda_2 + g_1 = 0 \quad g_2 \lambda_2 = -\frac{g_1}{2g_2}$$

with optimum solution $\lambda_2^{(*)}$ (r: raw)

The final solution of (*) is

$$\lambda_2^{(c)} = \begin{cases} H, & \text{if } \lambda_2^{(r)} \geq H \\ \lambda_2^{(r)}, & \text{if } L \leq \lambda_2^{(r)} \leq H \\ L, & \text{if } \lambda_2^{(r)} < L \end{cases} . \quad (c: \text{clipped})$$

λ_1 is computed from (**).

Still to clarify:

- o What is the best choice of the next pair (i,j) to update.
- o How to update the coefficients $\gamma_0, \gamma_1, \gamma_2$ in the run of SMO.
- o The algorithm converges, however, the right choice of (i,j) in each step accelerates the rate of convergence.
- o Osuna, Freund, Girosi (1997): generalization of SMO algorithm.

6.6. Kernels

Instead of applying SVM to the raw data ("attributes") x_i , apply it to transformed data ("features") $\phi(x_i)$.

ϕ is called feature mapping.

Rule: achieve better separability.

$$(1) \quad \max_{\lambda} g(\lambda) = \sum_{i=1}^n \lambda_i - \frac{1}{2} \sum_{i,j=1}^n y_i y_j \lambda_i \lambda_j x_i^T x_j$$

s.t. $0 \leq \lambda_i \leq C$

$$\sum_{i=1}^n \lambda_i y_i = 0$$

$g(\lambda)$ only depends on the inner products $x_i^T x_j$.

Substitute x_i by $\phi(x_i)$ and use some inner product

$\langle \cdot, \cdot \rangle$. Replace $x_i^T x_j$ by

$$\langle \phi(x_i), \phi(x_j) \rangle = K(x_i, x_j)$$

Remark: $K(x, y)$ is often easier to compute than $\langle \phi(x), \phi(y) \rangle$ itself.

Intuition: If $\phi(x), \phi(y)$ are close $\langle \phi(x), \phi(y) \rangle$ is large.

If $\phi(x) \perp \phi(y)$ then $\langle \phi(x), \phi(y) \rangle = 0$. Hence

$K(x, y)$ measures how similar x and y are.

Needed: an inner product in some feature space

$$\{\phi(x) \mid x \in \mathbb{R}^p\}$$

Example 6.2.

$$x, z \in \mathbb{R}^P, K(x, z) = \langle x, z \rangle^2 = \left(\sum_{i=1}^P x_i z_i \right)^2$$

Question: Is there some ϕ such that $\langle x, z \rangle^2$ is an inner product in the feature space.

$$p=2: \quad x = (x_1, x_2)^\top, \quad z = (z_1, z_2)^\top$$

$$\text{Use } \phi(x) = (x_1^2, x_2^2, x_1 x_2, x_2 x_1) : \mathbb{R}^2 \rightarrow \mathbb{R}^4$$

$$\begin{aligned} \langle \phi(x), \phi(z) \rangle &= x_1^2 z_1^2 + x_2^2 z_2^2 + x_1 x_2 z_1 z_2 + x_2 x_1 z_1 z_2 \\ &= x_1^2 z_1^2 + x_2^2 z_2^2 + 2 x_1 x_2 z_1 z_2 \\ &= (x_1 z_1 + x_2 z_2)^2 = \langle x, z \rangle^2 \end{aligned}$$

Example 6.3. (Gaussian Kernel)

$$x, z \in \mathbb{R}^P, \quad K(x, z) = \exp\left(-\frac{\|x - z\|^2}{2\sigma^2}\right)$$

Question: \exists feature mapping ϕ and a feature space with $\langle \cdot, \cdot \rangle$?

Def. 6.4. Kernel $K(x, z)$ is called valid, if there exists a feature function ϕ such that

$$K(x, z) = \langle \phi(x), \phi(z) \rangle \text{ for all } x, z \in \mathbb{R}^P.$$

Theorem 6.5. (Mercer)

Given $K: \mathbb{R}^P \times \mathbb{R}^P \rightarrow \mathbb{R}$. K is a valid kernel if and only if for any $\{x_1, \dots, x_n\}$ the kernel matrix

$$(K(x_i, x_j))_{ij=1, \dots, n} \text{ is u.u.o. } \underline{|}$$

Proof. \Rightarrow

$$\begin{aligned} K \text{ valid} \Rightarrow \exists \phi: K(x_i, x_j) &= \langle \phi(x_i), \phi(x_j) \rangle = \langle \phi(x_j), \phi(x_i) \rangle \\ &= K(x_j, x_i) \end{aligned}$$

Moreover,

$$\begin{aligned} z^T (K(x_i, x_j))_{ij} z &= z^T (\langle \phi(x_i), \phi(x_j) \rangle)_{ij} z \\ &= \sum_{k, e} z_k z_e \langle \phi(x_k), \phi(x_e) \rangle \\ &= \left\langle \sum_k z_k \phi(x_k), \sum_e z_e \phi(x_e) \right\rangle \geq 0 \quad \blacksquare \end{aligned}$$

Example 6 (Polynomial kernel)

$$K(x, z) = (x^T z + c)^d, \quad x, z \in \mathbb{R}^P, c \in \mathbb{R}, d \in \mathbb{N}, d \geq 2.$$

Feature space of dim ~~$\binom{p+d}{d}$~~ containing all monomials of degree $\leq d$.

Determine $\phi(x) \rightarrow \underline{\text{Ex.}}$ 1

Kernels can also be constructed over infinite dimensional spaces, e.g., function space or probability distributions.

Provides lots of modeling power.

The solution of the opt problem is still a convex problem with linear constraints.