

2. Fundamentals of Information Theory

Subchapter 2.1-2.4 only about discrete distribution.

2.1. Information Measures

Consider 2 random experiment with 3 outcomes, resp., and distributions by

$$(0.9, 0.05, 0.05)$$

$$(0.4, 0.3, 0.3)$$

We seek a measure of

uncertainty (about the outcome) } =
information (gained by the outcome) }

An appropriate measure was introduced by Shannon (48), namely entropy. Formal description & motivation.

The information content of some event E shall only depend on the probability $p = P(E)$.

Measure the information content by a function

$$h : [0,1] \rightarrow \mathbb{R}$$

satisfying (i) h continuous on $[0,1]$

$$(ii) h(p \cdot q) = h(p) + h(q), p, q \in [0,1]$$

$$(iii) \exists c > 1 : h\left(\frac{1}{c}\right) = 1$$

- (ii) Normalization, fixing the scale
- (iii) Let E_1, E_2 be independent events with prob. p and q , resp., then the event $E_1 \cap E_2$ has uncertainty $h(p) + h(q)$.

If (i), (ii), (iii) hold for some function h , then

$$h(p) = -\log_c(p), p \in [0, 1].$$

Consider description by discrete random variables X (r.v.) with finite support $\mathcal{X} = \{x_1, \dots, x_m\}$ and distribution $P(X=x_i) = p_i$, $p_i \geq 0$, $\sum_{i=1}^m p_i = 1$.

Entropy is defined as the average information content of the events $\{X=x_i\}$, $i=1, \dots, m$.

Def. 2.1.1. Fix $c > 1$, a constant.

$$\begin{aligned} H(X) &= - \sum_{i=1}^m P(X=x_i) \log_c P(X=x_i) \\ &= - \sum_{i=1}^m p_i \log_c p_i \end{aligned}$$

is called entropy of X (or of (p_1, \dots, p_m)).

Remarks 2.1.2.

- a) If $p_i = 0$ for some i , we set $0 \cdot \log 0 = 0$.
- b) $H(X)$ only depends on the probabilities, not on the support.

c) The Log-base is omitted, however fixed.

Common choices: $c = e = 2.7\dots$, $c = 2$, $c = 10, \dots$

d) Let $p(x)$ denote the prob. mass fct. (pmf)
or discrete density of X , i.e.,

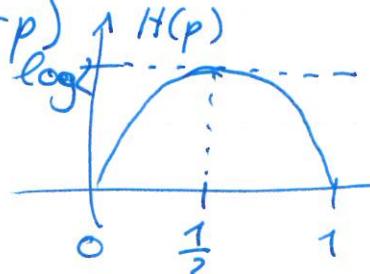
$$p : \mathcal{X} \rightarrow [0, 1] : x_i \mapsto p(x_i) = p_i$$

Then $H(X) = E\left[\log \frac{1}{p(X)}\right]$.

Examples 2.1-3.

a) $X \sim \text{Bin}(1, p)$, i.e., $P(X=0) = 1-p$, $P(X=1) = p$, $p \in [0, 1]$

$$H(X) = -p \log p - (1-p) \log(1-p)$$



b) $X \sim U(\{1, \dots, m\})$, i.e., $P(X=k) = \frac{1}{m}$, $k = 1, \dots, m$.

$$H(X) = -\sum_{i=1}^m \frac{1}{m} \log \frac{1}{m} = -\log \frac{1}{m} = \log m$$

Particularly: $m = 26$, $\log_2 26 = 4.7004$.

c) Frequencies of characters in English

A	B	C	-	...	Z
0.082	0.015	0.028			0.0007

$$\begin{aligned} H(X) &= -0.082 \log_2 0.082 - \dots - 0.0007 \log 0.0007 \\ &= 4.219 (< 4.7004 !) \end{aligned}$$

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Def. 2.1.3 Extension to 2-dim discrete random vectors. Let

(X, Y) be a discrete random vector with support

$X \times Y = \{x_1, \dots, x_m\} \times \{y_1, \dots, y_n\}$ and distribution

$$P(X=x_i, Y=y_j) = p_{ij}, \quad p_{ij} \geq 0, \quad \sum_{i,j} p_{ij} = 1.$$

Def. 2.1.4.

$$\begin{aligned} a) H(X, Y) &= - \sum_{i,j} P(X=x_i, Y=y_j) \log P(X=x_i, Y=y_j) \\ &= - \sum_{i,j} p_{ij} \log p_{ij} \end{aligned}$$

is called the joint entropy of (X, Y) .

$$\begin{aligned} b) H(X|Y) &= - \sum_{j=1}^n P(Y=y_j) \sum_{i=1}^m P(X=x_i | Y=y_j) \log P(X=x_i | Y=y_j) \\ &= - \sum_{i,j} P(X=x_i, Y=y_j) \log P(X=x_i | Y=y_j) \end{aligned}$$

is called conditional entropy of X given Y .

(or equivocation).

Th. 2.1.5. (Chain rule)

$$H(X, Y) = H(X) + H(Y|X) = H(Y) + H(X|Y). \quad \perp$$

Proof. Denote $p(x_i)$, $p(x_i, y_j)$, $p(y_j|x_i)$ corresponding p.m.f.

$$\begin{aligned} H(X, Y) &= - \sum_{i,j} p(x_i, y_j) [\log p(x_i, y_j) - \log p(x_i) + \log p(x_i)] \\ &= - \sum_{i,j} p(x_i, y_j) \log p(y_j|x_i) \\ &\quad - \underbrace{\sum_i \sum_j p(x_i, y_j) \log p(x_i)}_{= p(x_i)} \\ &= H(Y|X) + H(X) \end{aligned}$$

Second equality analogously. \blacksquare

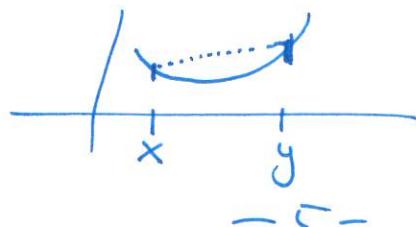
Lemma 2.1.6. (Jensen inequality)

If f is a convex function and X a r.v., then

$$E(f(X)) \geq f(E(X)). \quad (*)$$

(*) holds for any r.v. (not only discrete) as long as the expectations are well defined.

f is called convex if $f(\alpha x + (1-\alpha)y) \leq \alpha f(x) + (1-\alpha)f(y)$



$$\alpha \in [0,1], x, y \in D(f)$$

For discrete r.v. with distribution (p_1, \dots, p_m)

(*) reads

$$\sum_{i=1}^m p_i f(x_i) \geq R\left(\sum_{i=1}^m p_i x_i\right)$$

$$\forall x_1, \dots, x_m \in \text{dom}(R) \quad \forall p_i \geq 0, \sum_{i=1}^m p_i = 1.$$

Proof. \rightarrow Ex.

Lemma 2.1.6. (log-sum inequality)

Let $a_i, b_i \geq 0$, $i=1, \dots, m$. Then

$$\sum_i a_i \log \frac{a_i}{b_i} \geq \sum_i a_i \log \frac{\sum_j a_j}{\sum_j b_j}$$

with equality if and only if $\frac{a_i}{b_i} = \text{const.}$

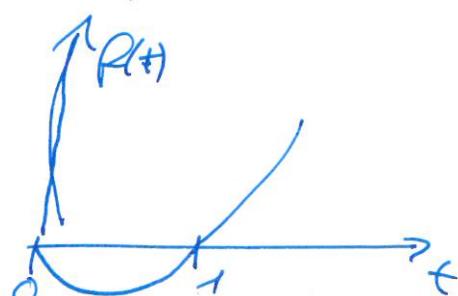
We use conventions: $0 \cdot \log 0 = 0$

$a \log \frac{a}{0} = \infty$, if $a > 0$

$0 \log \frac{0}{0} = 0$ (by continuity)

Proof. $f(t) = t \cdot \log t$, $t \geq 0$, is strictly convex.

Since $f''(t) = \frac{1}{t} > 0$, $t > 0$.



w.l.o.g. assume $a_i, b_i \geq 0$.

By convexity of f

$$\sum_{i=1}^m \alpha_i f(t_i) \geq f\left(\sum_{i=1}^m \alpha_i t_i\right), \quad \alpha_i \geq 0, \quad \sum_{i=1}^m \alpha_i = 1$$

Setting $\alpha_i = \frac{b_i}{\sum_j b_j}$, $t_i = \frac{a_i}{b_i}$ it follows

$$\sum_i \frac{b_i}{\sum_j b_j} \frac{a_i}{b_i} \log \frac{a_i}{b_i} \geq \sum_i \frac{b_i}{\sum_j b_j} \frac{a_i}{b_i} \log \left(\sum_i \frac{b_i}{\sum_j b_j} \frac{a_i}{b_i} \right)$$

$$\Leftrightarrow \frac{\sum_i a_i \log \frac{a_i}{b_i}}{\sum_j b_j} \geq \frac{\sum_i a_i}{\sum_j b_j} \log \frac{\sum_i a_i}{\sum_j b_j} \quad \blacksquare$$

Corollary 2.1.7. Let $p = (p_1, \dots, p_m)$, $q = (q_1, \dots, q_m)$

be stoch. vectors, i.e., $p_i \geq 0, q_i \geq 0, \sum_i p_i = \sum_i q_i = 1$.

Then

$$-\sum_{i=1}^m p_i \log p_i \leq -\sum_{i=1}^m p_i \log q_i \quad \not\propto$$

" if and only if $p=q$. \rightarrow

Proof. In La. 2.1.6. set

$a_i = p_i$, $b_i = q_i$ and observe that $\sum_i p_i = \sum_i q_i = 1$ \blacksquare